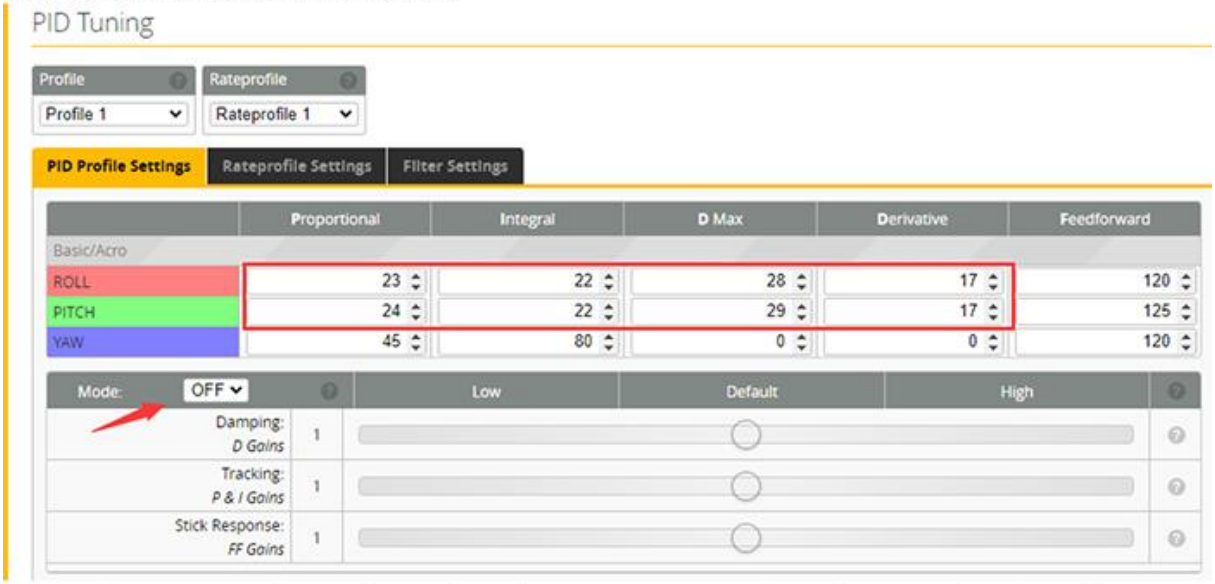
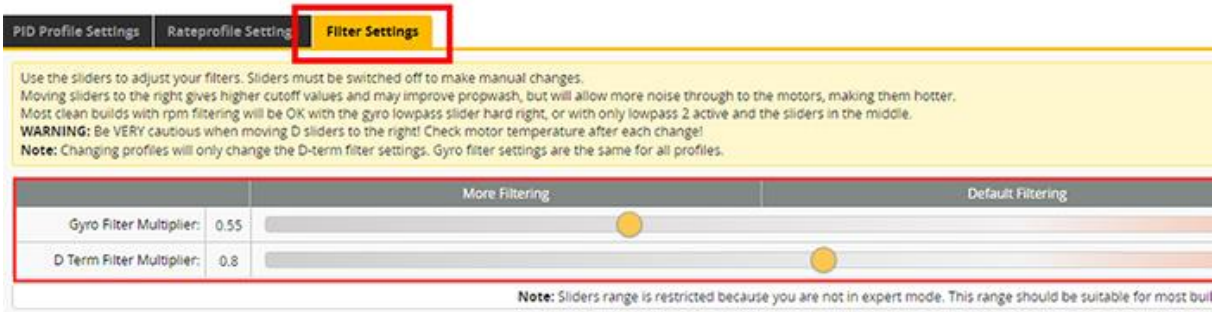
ATTENTION

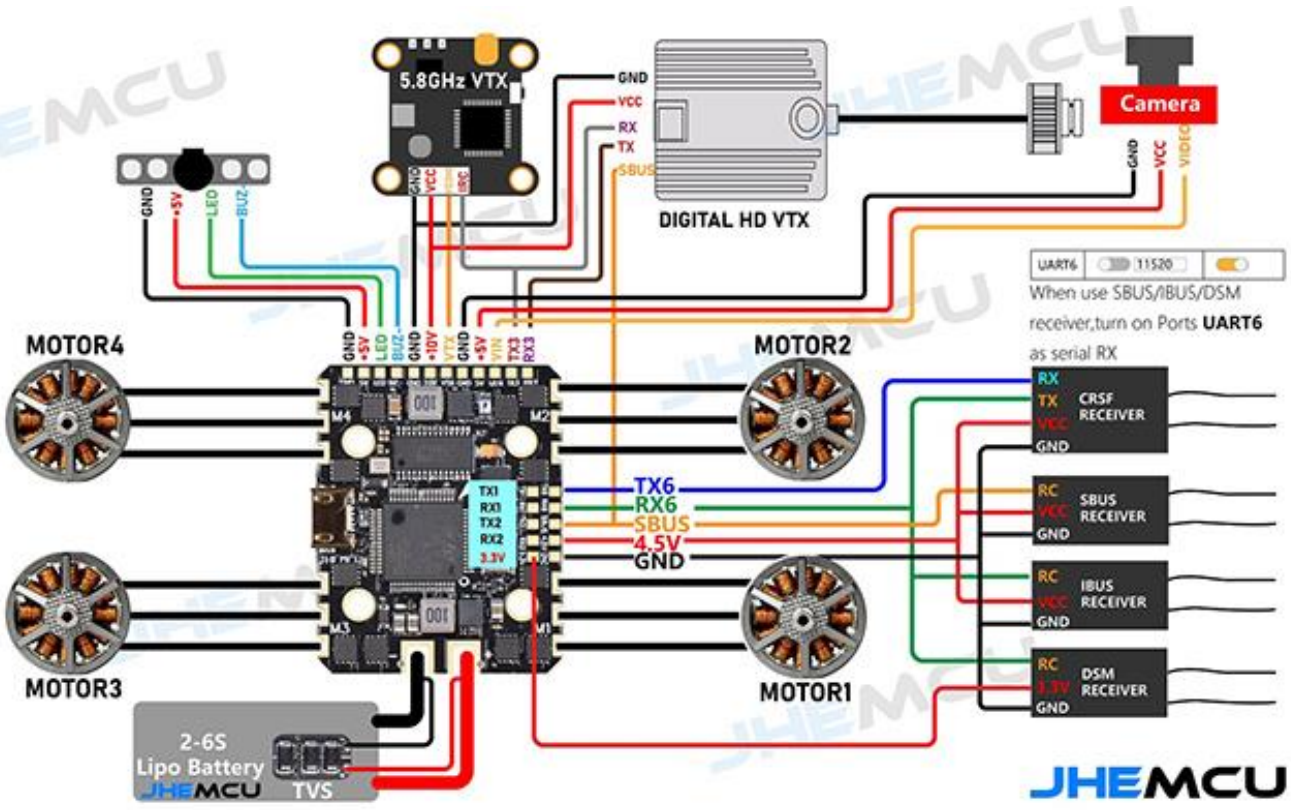
Please note that if the flight control is restored to the factory or the firmware is upgraded, it is recommended to refer to the following for PID and Filter settings. (writing the configuration file provided by jhemcu will automatically complete the modification)



1. Set the arrow to "off" and then adjust the PID parameters with reference to the above figure.



2. Adjust the filter setting as shown in the figure. The value in the first row is 0.55, and the value in the second row is 0.8 (sliding slider)


5.8GHz VTX
GND
VCC
RX
TX
SBUS
DIGITAL HD VTX
Camera
GND
VCC
VIDEO
GND
5V
LED
BUZ
UART6
115200
When use SBUS/iBUS/DSM
receiver,turn on Ports UART6
as serial RX
MOTOR4
MOTOR2
MOTOR3
MOTOR1
M4
M2
M3
M1
TX1
RX1
TX2
RX2
3.3V
TX6
RX6
SBUS
4.5V
GND
RX
TX
VCC
GND
CRSF
RECEIVER
RC
VCC
GND
SBUS
RECEIVER
RC
VCC
GND
IBUS
RECEIVER
RC
3.3V
GND
DSM
RECEIVER
2-6S
Lipo Battery
JHEMCU
TVS
JHEMCU